

# Distributions

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These notes are based on the exposition in [GeSh68] and [Ho03]. Let  $\Omega$  be an open set in  $\mathbb{R}^n$  and  $C_0^\infty(\Omega)$  the vector space of all compactly supported functions on  $\Omega$  which are infinitely differentiable.

**Definition 1.** A distribution on  $\Omega$  is a linear map  $u : C_0^\infty(\Omega) \rightarrow \mathbb{R}$  such that for every compact subset  $K$  in  $\Omega$  there is a constant  $C_K$  and a positive integer  $N$  so that

$$|\langle u, \phi \rangle| \leq C_K \sup_{x \in K} \sum_{|\alpha| \leq N} |(\partial^\alpha \phi)(x)|$$

for all  $\phi \in C_0^\infty(\Omega)$  with support in  $K$ .

If  $f$  is a locally integrable function on  $\Omega$  then  $f$  is a distribution defined by

$$\langle f, \phi \rangle = \int_{\Omega} f(x) \phi(x) dx, \quad \forall \phi \in C_0^\infty(\Omega).$$

The Dirac delta function  $\delta(x)$  is a distribution defined by

$$\langle \delta(x), \phi(x) \rangle = \phi(0), \quad \forall \phi \in C_0^\infty(\Omega).$$

For any smooth function  $u$  on  $\Omega$ , by the integration by parts formula, we have

$$\int_{\Omega} (\partial_i u)(x) \phi(x) dx = - \int_{\Omega} u(x) (\partial_i \phi)(x) dx, \quad \forall \phi \in C_0^\infty(\Omega).$$

This suggests a natural definition of the derivative of a distribution.

**Definition 2.** If  $u$  is a distribution on  $\Omega$  then  $\partial_i u$  is a distribution defined by

$$\langle \partial_i u, \phi \rangle = -\langle u, \partial_i \phi \rangle.$$

We want to give meaning to objects such as  $\delta(|x|^2 - 1)$  as a distribution on  $\mathbb{R}^n$ . Suppose  $f$  is a real valued  $C^1$  function on  $\mathbb{R}^n$  and  $S$  the zero set of  $f$ , that is  $S = \{x \in \mathbb{R}^n : f(x) = 0\}$ ; further assume that  $(\nabla f)(x) \neq 0$  at every point of  $S$ . We may define  $\delta(f)$  using pullbacks as in Hormander's Vol 1???? but we want to give a computational definition.

**Definition 3.** If  $f$  is a real valued function  $C^1$  function on  $\mathbb{R}^n$  with  $(\nabla f)(x) \neq 0$  for every  $x \in S$ , the zero set  $f(x) = 0$ . Then we define the distribution  $\delta(f)$  as

$$\langle \delta(f), \phi \rangle = \int_S \frac{\phi}{|\nabla f|} dS.$$

Let us see why this is the natural definition of  $\delta(\phi)$ . We will write  $x = (x', x_n)$  with  $x' \in \mathbb{R}^{n-1}$ ,  $x_n \in \mathbb{R}$ . If  $p$  is any point on  $S$  then  $(\nabla f)(p) \neq 0$ , say  $(\partial_n f)(p) \neq 0$ ; then by the inverse function theorem applied to the map

$$x \mapsto (x', f(x)), \quad (1)$$

there are neighborhoods  $U$  of  $p$  and  $V$  of  $(p', 0)$  and a  $C^1$  inverse  $y \mapsto (y', g(y))$  of (1) so that  $g(f(x)) = x_n$ ,  $f(g(y)) = y_n$  for  $x \in U$ ,  $y \in V$ . We assume that these relations hold for all  $x, y \in \mathbb{R}^n$  - the actual situation can be handled by a partition of unity argument.

The surface  $S : f(x) = 0$  is mapped to the region  $y_n = 0$ ; further  $S$  is also given by the equation  $x_n = h(x')$  where we define  $h(x') := g(x', 0)$ . Consider the following formal computation with a change of variables  $x \mapsto y = (x', f(x))$  (note  $y' = x'$  and  $dy = |(\partial_n f)(x)| dx$ );

$$\begin{aligned} \langle \delta(f), \phi \rangle &= \int_{\mathbb{R}^n} \delta(f(x)) \phi(x) dx = \int_{\mathbb{R}^n} \delta(y_n) \frac{\phi(x)}{|(\partial_n f)(x)|} dy = \int_{\mathbb{R}^{n-1}, y_n=0} \frac{\phi(x)}{|(\partial_n f)(x)|} dy' \\ &= \int_{\mathbb{R}^{n-1}} \frac{\phi(x', h(x'))}{|(\partial_n f)(x', h(x'))|} dx' = \int_S \frac{1}{\sqrt{1 + |\nabla_{x'} h|^2}} \frac{\phi}{|\partial_n f|} dS. \end{aligned}$$

Now  $f(x', h(x')) = 0$  so  $\nabla_{x'} f + \partial_n f \nabla_{x'} h = 0$  so

$$1 + |\nabla_{x'} h|^2 = \frac{(\partial_n f)^2 + |\nabla_{x'} f|^2}{(\partial_n f)^2} = \frac{|\nabla f|^2}{|\partial_n f|^2}.$$

Hence formally

$$\langle \delta(f), \phi \rangle = \int_S \frac{\phi}{|\nabla f|} dS.$$

One useful distribution is the fundamental solution of the wave equation in three space dimensions, that is a distribution  $G(x, t)$  so that

$$\begin{aligned} (\square G)(x, t) &:= (\partial_t^2 G - \Delta_x G)(x, t) = \delta(x, t), \quad (x, t) \in \mathbb{R}^3 \times \mathbb{R} \\ G(x, t) &= 0, \quad \text{for } t < 0. \end{aligned}$$

It takes considerable effort to show that

$$G(x, t) = \frac{1}{4\pi} \frac{\delta(t - |x|)}{|x|}$$

that is for any  $\phi(x, t) \in C_0^\infty(\mathbb{R}^3 \times \mathbb{R})$  if we define the distribution  $G$  as

$$\langle G, \phi \rangle = \frac{1}{4\pi} \int_{\mathbb{R}^3} \frac{\phi(x, |x|)}{|x|} dx \quad (2)$$

then  $\langle \square G, \phi \rangle = \phi(0, 0)$ . Note that from (2) it is clear that  $\langle G, \phi \rangle = 0$  for any  $\phi$  supported in  $t < 0$ .

## References

- [GeSh68] I M Gelfand and G E Shilov. Generalized Functions, Volume 2: Spaces of Fundamental and Generalized Functions, Academic Press (1968).
- [Ho03] Lars Hormander. The Analysis of Linear Partial Differential Operators I: Distribution Theory and Fourier Analysis (Classics in Mathematics), Springer Verlag (2003).